Artificial Intelligence
A Modern Approach
Fourth Edition
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Artificial Intelligence
A Modern Approach
Fourth Edition

Stuart J. Russell and Peter Norvig

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For Loy, Gordon, Lucy, George, and Isaac — S.J.R.

For Kris, Isabella, and Juliet — P.N.
Preface

Artificial Intelligence (AI) is a big field, and this is a big book. We have tried to explore the full breadth of the field, which encompasses logic, probability, and continuous mathematics; perception, reasoning, learning, and action; fairness, trust, social good, and safety; and applications that range from microelectronic devices to robotic planetary explorers to online services with billions of users.

The subtitle of this book is “A Modern Approach.” That means we have chosen to tell the story from a current perspective. We synthesize what is now known into a common framework, recasting early work using the ideas and terminology that are prevalent today. We apologize to those whose subfields are, as a result, less recognizable.

New to this edition

This edition reflects the changes in AI since the last edition in 2010:

- We focus more on machine learning rather than hand-crafted knowledge engineering, due to the increased availability of data, computing resources, and new algorithms.
- Deep learning, probabilistic programming, and multiagent systems receive expanded coverage, each with their own chapter.
- The coverage of natural language understanding, robotics, and computer vision has been revised to reflect the impact of deep learning.
- The robotics chapter now includes robots that interact with humans and the application of reinforcement learning to robotics.
- Previously we defined the goal of AI as creating systems that try to maximize expected utility, where the specific utility information—the objective—is supplied by the human designers of the system. Now we no longer assume that the objective is fixed and known by the AI system; instead, the system may be uncertain about the true objectives of the humans on whose behalf it operates. It must learn what to maximize and must function appropriately even while uncertain about the objective.
- We increase coverage of the impact of AI on society, including the vital issues of ethics, fairness, trust, and safety.
- We have moved the exercises from the end of each chapter to an online site. This allows us to continuously add to, update, and improve the exercises, to meet the needs of instructors and to reflect advances in the field and in AI-related software tools.
- Overall, about 25% of the material in the book is brand new. The remaining 75% has been largely rewritten to present a more unified picture of the field. 22% of the citations in this edition are to works published after 2010.

Overview of the book

The main unifying theme is the idea of an **intelligent agent**. We define AI as the study of agents that receive percepts from the environment and perform actions. Each such agent implements a function that maps percept sequences to actions, and we cover different ways to represent these functions, such as reactive agents, real-time planners, decision-theoretic
systems, and deep learning systems. We emphasize learning both as a construction method for competent systems and as a way of extending the reach of the designer into unknown environments. We treat robotics and vision not as independently defined problems, but as occurring in the service of achieving goals. We stress the importance of the task environment in determining the appropriate agent design.

Our primary aim is to convey the ideas that have emerged over the past seventy years of AI research and the past two millennia of related work. We have tried to avoid excessive formality in the presentation of these ideas, while retaining precision. We have included mathematical formulas and pseudocode algorithms to make the key ideas concrete; mathematical concepts and notation are described in Appendix A and our pseudocode is described in Appendix B.

This book is primarily intended for use in an undergraduate course or course sequence. The book has 28 chapters, each requiring about a week’s worth of lectures, so working through the whole book requires a two-semester sequence. A one-semester course can use selected chapters to suit the interests of the instructor and students. The book can also be used in a graduate-level course (perhaps with the addition of some of the primary sources suggested in the bibliographical notes), or for self-study or as a reference.

Throughout the book, important points are marked with a triangle icon in the margin. Wherever a new term is defined, it is also noted in the margin. Subsequent significant uses of the term are in bold, but not in the margin. We have included a comprehensive index and an extensive bibliography.

The only prerequisite is familiarity with basic concepts of computer science (algorithms, data structures, complexity) at a sophomore level. Freshman calculus and linear algebra are useful for some of the topics.

**Online resources**

Online resources are available through pearsonhighered.com/cs-resources or at the book’s Web site, aima.cs.berkeley.edu. There you will find:

- Exercises, programming projects, and research projects. These are no longer at the end of each chapter; they are online only. Within the book, we refer to an online exercise with a name like “Exercise 6.NARY.” Instructions on the Web site allow you to find exercises by name or by topic.
- Implementations of the algorithms in the book in Python, Java, and other programming languages (currently hosted at github.com/aimacode).
- A list of over 1400 schools that have used the book, many with links to online course materials and syllabi.
- Supplementary material and links for students and instructors.
- Instructions on how to report errors in the book, in the likely event that some exist.

**Book cover**

The cover depicts the final position from the decisive game 6 of the 1997 chess match in which the program Deep Blue defeated Garry Kasparov (playing Black), making this the first time a computer had beaten a world champion in a chess match. Kasparov is shown at the
top. To his right is a pivotal position from the second game of the historic Go match between former world champion Lee Sedol and DeepMind’s ALPHAGO program. Move 37 by ALPHAGO violated centuries of Go orthodoxy and was immediately seen by human experts as an embarrassing mistake, but it turned out to be a winning move. At top left is an Atlas humanoid robot built by Boston Dynamics. A depiction of a self-driving car sensing its environment appears between Ada Lovelace, the world’s first computer programmer, and Alan Turing, whose fundamental work defined artificial intelligence. At the bottom of the chess board are a Mars Exploration Rover robot and a statue of Aristotle, who pioneered the study of logic; his planning algorithm from De Motu Animalium appears behind the authors’ names. Behind the chess board is a probabilistic programming model used by the UN Comprehensive Nuclear-Test-Ban Treaty Organization for detecting nuclear explosions from seismic signals.

Acknowledgments

It takes a global village to make a book. Over 600 people read parts of the book and made suggestions for improvement. The complete list is at aima.cs.berkeley.edu/ack.html; we are grateful to all of them. We have space here to mention only a few especially important contributors. First the contributing writers:

- Judea Pearl (Section 13.5, Causal Networks);
- Vikash Mansinghka (Section 15.3, Programs as Probability Models);
- Michael Wooldridge (Chapter 18, Multiagent Decision Making);
- Ian Goodfellow (Chapter 21, Deep Learning);
- Jacob Devlin and Ming-Wei Chang (Chapter 24, Deep Learning for Natural Language);
- Jitendra Malik and David Forsyth (Chapter 25, Computer Vision);
- Anca Dragan (Chapter 26, Robotics).

Then some key roles:

- Cynthia Yeung and Malika Cantor (project management);
- Julie Sussman and Tom Galloway (copyediting and writing suggestions);
- Omari Stephens (illustrations);
- Tracy Johnson (editor);
- Erin Ault and Rose Kernan (cover and color conversion);
- Nalin Chhibber, Sam Goto, Raymond de Lacaze, Ravi Mohan, Ciaran O’Reilly, Amit Patel, Dragomir Radiv, and Samagra Sharma (online code development and mentoring);
- Google Summer of Code students (online code development).

**Stuart would like to thank** his wife, Loy Sheflott, for her endless patience and boundless wisdom. He hopes that Gordon, Lucy, George, and Isaac will soon be reading this book after they have forgiven him for working so long on it. RUGS (Russell’s Unusual Group of Students) have been unusually helpful, as always.

**Peter would like to thank** his parents (Torsten and Gerda) for getting him started, and his wife (Kris), children (Bella and Juliet), colleagues, boss, and friends for encouraging and tolerating him through the long hours of writing and rewriting.
About the Authors

Stuart Russell was born in 1962 in Portsmouth, England. He received his B.A. with first-class honours in physics from Oxford University in 1982, and his Ph.D. in computer science from Stanford in 1986. He then joined the faculty of the University of California at Berkeley, where he is a professor and former chair of computer science, director of the Center for Human-Compatible AI, and holder of the Smith–Zadeh Chair in Engineering. In 1990, he received the Presidential Young Investigator Award of the National Science Foundation, and in 1995 he was cowinner of the Computers and Thought Award. He is a Fellow of the American Association for Artificial Intelligence, the Association for Computing Machinery, and the American Association for the Advancement of Science, an Honorary Fellow of Wadham College, Oxford, and an Andrew Carnegie Fellow. He held the Chaire Blaise Pascal in Paris from 2012 to 2014. He has published over 300 papers on a wide range of topics in artificial intelligence. His other books include The Use of Knowledge in Analogy and Induction, Do the Right Thing: Studies in Limited Rationality (with Eric Wefald), and Human Compatible: Artificial Intelligence and the Problem of Control.

Peter Norvig is currently a Director of Research at Google, Inc., and was previously the director responsible for the core Web search algorithms. He co-taught an online AI class that signed up 160,000 students, helping to kick off the current round of massive open online classes. He was head of the Computational Sciences Division at NASA Ames Research Center, overseeing research and development in artificial intelligence and robotics. He received a B.S. in applied mathematics from Brown University and a Ph.D. in computer science from Berkeley. He has been a professor at the University of Southern California and a faculty member at Berkeley and Stanford. He is a Fellow of the American Association for Artificial Intelligence, the Association for Computing Machinery, the American Academy of Arts and Sciences, and the California Academy of Science. His other books are Paradigms of AI Programming: Case Studies in Common Lisp, Verbmobile: A Translation System for Face-to-Face Dialog, and Intelligent Help Systems for UNIX.

The two authors shared the inaugural AAAI/EAAI Outstanding Educator award in 2016.
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