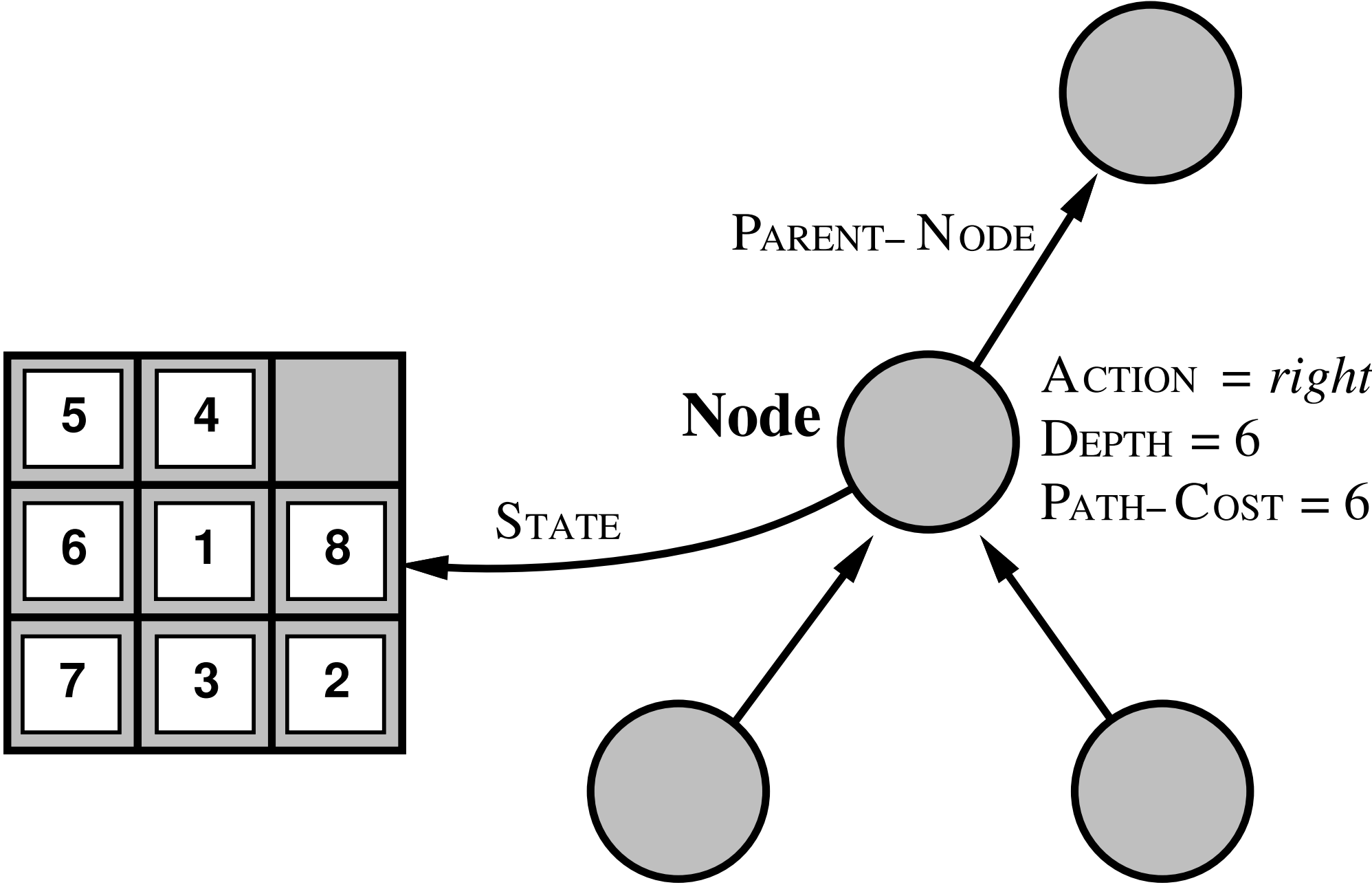
PARENT- NODE
Node
ACTION = *right*
DEPTH = 6
PATH- COST = 6
STATE
5
4
6
1
8
7
3
2