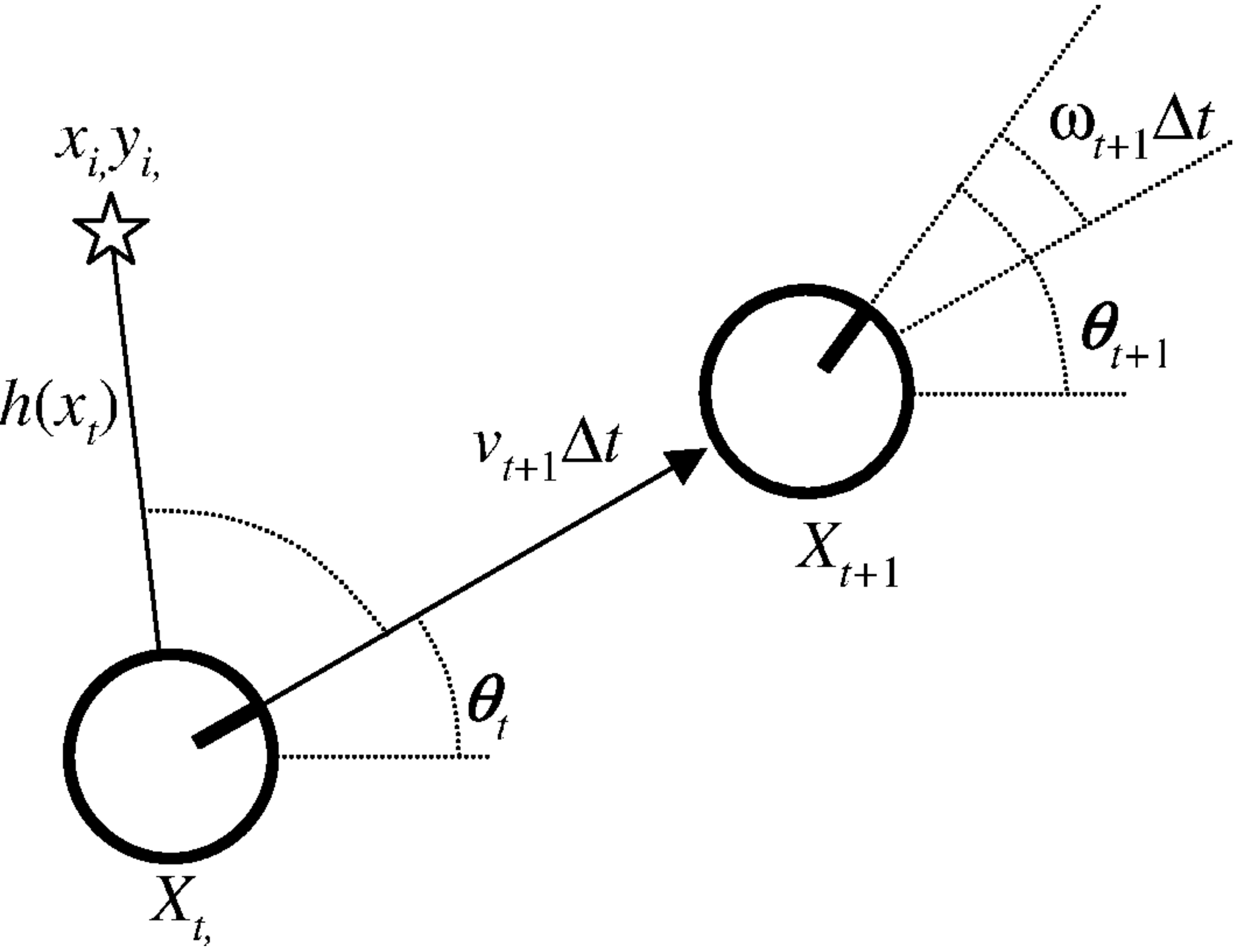
$x_i, y_i,$
$h(x_t)$
θ_t
$X_t,$
$v_{t+1}\Delta t$
$\omega_{t+1}\Delta t$
θ_{t+1}
X_{t+1}