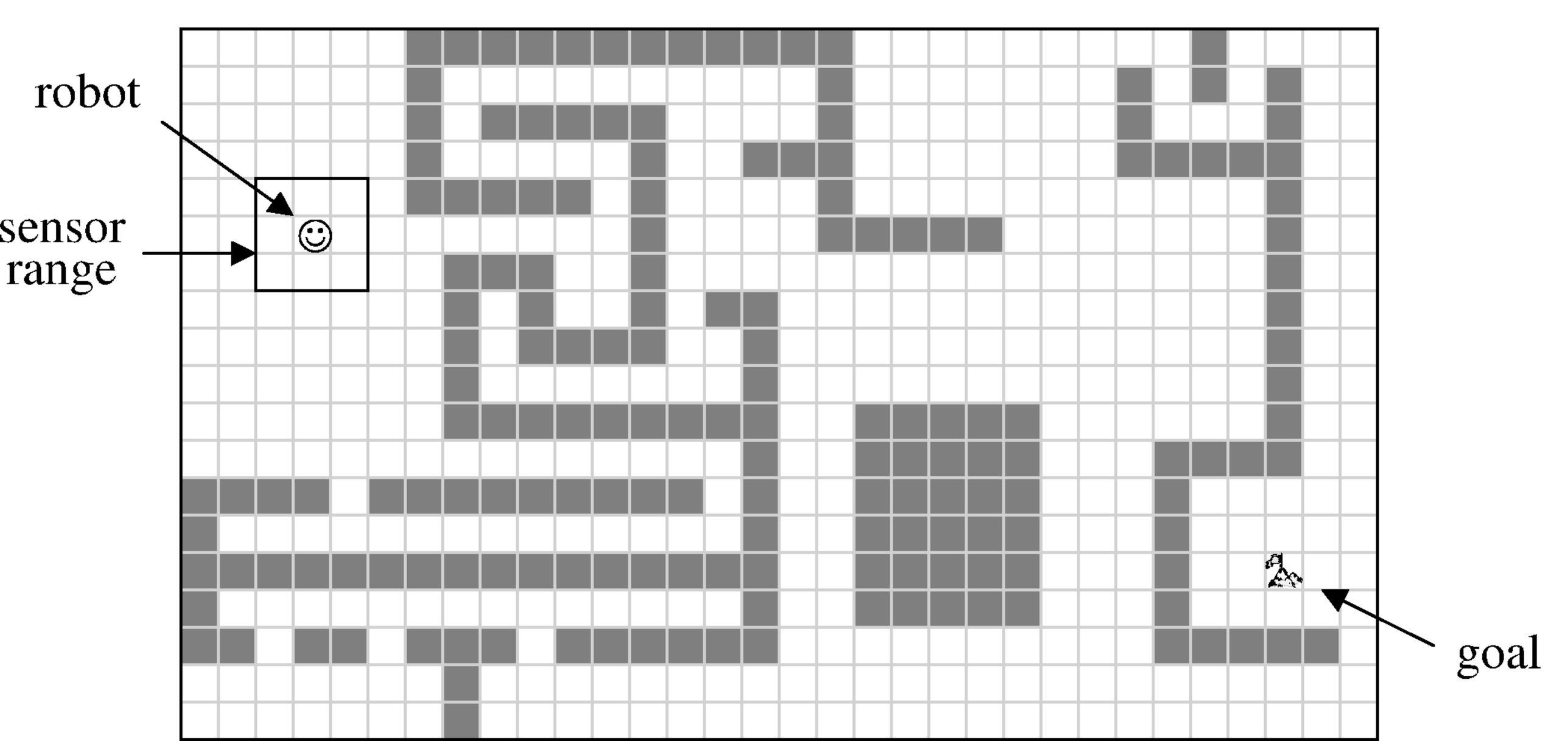
robot
sensor
range
goal